

Short  
Takes  
331



## Determinants Part 2 : Two applications

- Recall the recursive definition (Laplace expansion)

$$\det A = \sum_{j=1}^N a_{1j} (-1)^{1+j} \det A_{1j}$$

This motivates us to define the so-called cofactor matrix C

$$[C]_{ij} = (-1)^{i+j} \det A_{ij}.$$

Then,

$$\begin{aligned} [A \cdot C^T]_{ij} &= \sum_{k=1}^N a_{ik} C_{jk} = \sum_{k=1}^N a_{ik} (-1)^{j+k} \det A_{jk} \\ &= \begin{cases} \det A & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases} \end{aligned}$$

The same holds for  $C^T A$ .

$$\text{Thus, } AC^T = C^T A = \det A \cdot \mathbf{1} \Rightarrow A \frac{C^T}{\det A} = \frac{C^T}{\det A} A = \mathbf{1},$$

$$\text{i.e. } A^{-1} = \frac{C^T}{\det A}.$$

"the inverse is equal to the cofactor<sup>T</sup> divided by the determinant"

- You can regard this as the application of Cramer's rule to the problem

$$\begin{array}{ccc} A \cdot M = \mathbf{1} & \Leftrightarrow & A \vec{M}_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \text{ \& } A \vec{M}_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix} \text{ \& } \dots \\ & & \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \\ M = \begin{pmatrix} \vec{M}_1 & \vec{M}_2 & \dots & \vec{M}_N \end{pmatrix} & & \begin{matrix} \text{"E}_1 & & \text{"E}_2 \end{matrix} \\ & & \left( \begin{matrix} \downarrow & \downarrow & & \downarrow \end{matrix} \right) \end{array}$$

$$[\vec{M}_1]_i = \frac{1}{\det A} (-1)^{1+i} \det A_{1i}, \quad [\vec{M}_2]_i = \frac{1}{\det A} (-1)^{2+i} \det A_{2i}, \dots$$

$$M_{11} = [\vec{M}_1]_1 = \begin{vmatrix} 1 & a_{12} & a_{13} & \dots \\ 0 & a_{22} & \dots & \\ \vdots & \vdots & & \end{vmatrix} \cdot \frac{1}{\det A} \quad \dots$$

$$M_{21} = [\vec{M}_1]_2 = \begin{vmatrix} a_{11} & 1 & a_{13} & \dots \\ a_{21} & 0 & a_{23} & \dots \\ \vdots & \vdots & & \end{vmatrix} \frac{1}{\det A}$$

• Given  $N \times N$  problem

$B\vec{x} = 0$ , we always have at least  $\vec{x} = 0$  as a solution.

- If  $\det B \neq 0$ , then  $\vec{x} = 0$  is the only solution.
  - If  $\det B = 0$ , then there is an infinite number of solutions because the columns of  $B$  are linearly dependent.  
(not enough constraints to force  $\vec{x} = 0$ )
- non-wishing!

\* This is useful when calculating the so-called eigenvectors & eigenvalues of a matrix (future video on this!)...

Eigenvectors of  $M$ : nonzero vectors such that  $\exists \lambda$  (scalar) for which

$$M\vec{v} = \lambda\vec{v}$$

↑ eigenvectors      ↑ eigenvalues

→ How do we solve this problem? (find  $\lambda$  &  $\vec{v}$ )

$(M - \lambda I)\vec{v} = 0 \Rightarrow \vec{v} = 0$  ??? Not the solution we want!

To have  $\vec{v} \neq 0$ , it must be that

$$\det(M - \lambda \mathbb{1}) = 0$$

→ "secular equation"

It fully determines the allowed values of  $\lambda$ .

For example,

$$M = \begin{pmatrix} 1 & 1 \\ 2 & 0 \end{pmatrix} \Rightarrow (M - \lambda \mathbb{1}) = \begin{pmatrix} 1 - \lambda & 1 \\ 2 & -\lambda \end{pmatrix}$$

$$\det(M - \lambda \mathbb{1}) = \lambda(\lambda - 1) - 2 \stackrel{!}{=} 0$$

↳ quadratic eq. for  $\lambda$ .

