

Short
Takes
331



Linear systems of equations. Part 2.

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases}$$

Using matrices and vectors, we can rewrite it as

$$\boxed{A\vec{x} = \vec{b}}$$

our job is to solve for \vec{x} .

$m > n$: more eqs. than unknowns \rightarrow no solution

$m = n$: as many eqs. as unknowns \rightarrow unique solution

$m < n$: fewer eqs. than unknowns \rightarrow infinitely many solutions

"typically"

Caveats: degeneracy & consistency

\downarrow
eqs. contain
"superfluous" information

\rightarrow eqs. contain
"inconsistent" information

E.g.

$$\begin{cases} x_1 + 2x_2 = 9 \\ -2x_1 - 4x_2 = -18 \end{cases}$$

Second eq. is -2 times the first.
 \rightarrow they are linearly dependent!

E.g.

$$\begin{cases} 2x_1 + 3x_2 = -1 \\ -2x_1 - 3x_2 = 7 \end{cases}$$

$\rightarrow 0 = 6 \otimes ???$

- Solving the problem amounts to putting A on the other side of the equation:

$$A\vec{x} = \vec{b} \rightarrow A^{-1}A\vec{x} = A^{-1}\vec{b} \rightarrow \boxed{\vec{x} = A^{-1}\vec{b}}$$

\downarrow
 $A^{-1}A = \mathbf{1}$

If A^{-1} exists, the above operations are allowed and the solution vector \vec{x} is unique.

- How do we know when A^{-1} exists?
- How can one construct it?
- Is there a way to find \vec{x} directly without going through finding A^{-1} ?

Note: Knowing A^{-1} allows us to solve for \vec{x} for any given \vec{b} .
Therefore, knowing \vec{x} for a particular \vec{b} is a lot less information.

To gain intuition, let's look at some simple cases...

Case 1:

$$A = \begin{pmatrix} 1 & & & 0 \\ & 1 & & \\ & & \ddots & \\ 0 & & & 1 \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

$n \times n$

$$A\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \rightarrow \text{trivial!}$$

$$\begin{matrix} x_1 = b_1 \\ x_2 = b_2 \\ \vdots \end{matrix}$$

Case 2:

$$A = \begin{pmatrix} d_1 & & & 0 \\ & d_2 & & \\ & & \ddots & \\ 0 & & & d_n \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

$$A\vec{x} = \begin{pmatrix} d_1 x_1 \\ d_2 x_2 \\ \vdots \\ d_n x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \rightarrow \text{still rather trivial...}$$

$$\begin{matrix} x_1 = b_1/d_1 \\ x_2 = b_2/d_2 \\ \vdots \end{matrix}$$

must have $d_k \neq 0 \forall k$

• what if some $d_k = 0$?

↳ the corresponding x_k are arbitrary
& the solution is not unique, if $b_k = 0$.

If $b_k \neq 0$, there is a contradiction \rightarrow no solution.
(Consistency?)

Case 3:

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & 0 & a_{33} & \ddots & \vdots \\ 0 & & & & a_{nn} \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

$$A\vec{x} = ?$$

"upper triangular"

$$= \begin{pmatrix} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ a_{22}x_2 + \dots + a_{2n}x_n \\ \vdots \\ a_{nn}x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

→

* $x_n = b_n / a_{nn}$ (assuming $a_{nn} \neq 0$)

* $a_{n-1,n-1}x_{n-1} + a_{n-1,n}x_n = b_{n-1}$

known from previous eqn.

use it to solve for x_{n-1} .
will need

$a_{n-1,n-1} \neq 0$

* The next eqn. will involve x_{n-2}, x_{n-1}, x_n , but we already know the last two, so we use them to find x_{n-2} .

That will require $a_{n-2,n-2} \neq 0$.

* Continuing in this fashion we solve for all x_i . We will end up requiring $a_{ii} \neq 0$, i.e. must have non-zero diagonal elements.

Lower triangular systems are solved in the same way, but starting from the top.

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