

Short
Takes
331



Matrix multiplication (part 2): mechanics & cost

Suppose $A \in \mathbb{R}^{m \times n}$, $\vec{v} \in \mathbb{R}^n$, $\vec{w} \in \mathbb{R}^n$

• $\vec{v} \cdot \vec{w} = c$ $c \in \mathbb{R}$

$\left(\underbrace{\quad\quad\quad}_n \right) \left(\begin{array}{c} | \\ | \\ | \end{array} \right) \Bigg\}^n \rightarrow \underline{n \text{ multiplications \& additions}}$
 $\mathcal{O}(n)$

• $A\vec{v} = \vec{u}$, $\vec{u} \in \mathbb{R}^m$

$\left(\begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \vdots \end{array} \right) \left(\begin{array}{c} | \\ | \\ | \end{array} \right) \Bigg\}^n = \left(\begin{array}{c} | \\ | \\ | \end{array} \right) \Bigg\}^m$
 $\rightarrow \underline{m \text{ times}}$
 $\underline{n \text{ multiplications \& additions}}$
 $\mathcal{O}(m \times n)$

If A is square of size $n \times n \rightarrow \mathcal{O}(n^2)$

• Similarly, matrix-matrix products require $\mathcal{O}(m \times n \times p)$ if the matrices involved are of size $m \times n$ and $n \times p$.

For square matrices this becomes $\mathcal{O}(n^3)$

$\left(\begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \vdots \end{array} \right) \left(\begin{array}{c} | \\ | \\ | \\ \dots \end{array} \right) \Bigg\}^n = \left(\begin{array}{c} | \\ | \\ | \end{array} \right) \Bigg\}^m$
 $\underbrace{\quad\quad\quad}_n \quad \underbrace{\quad\quad\quad}_p \quad \underbrace{\quad\quad\quad}_p$

Can we do better?

Take for example matrix-vector multiplication ...

n times vector-vector n -component multiplication

↓
?

↓
?

We can improve on this in some special cases
e.g. Fourier transform
 $O(n \log n)$

We can improve on this e.g. if there are many zeros: sparse matrices, such as

$$\begin{pmatrix} 1 & -1 & 0 & \dots \\ 0 & 1 & -1 & 0 & \dots \\ a & 0 & 1 & -1 & 0 & \dots \\ & & & \ddots & \ddots & \ddots \end{pmatrix}$$

Here the cost of vector-vector mult. is 2, not n .

→ $O(2n)$ instead of $O(n^2)$

→ It's important to know different kinds of matrices and their properties. → next video!

→ This will help us solve linear problems in physics.

$$A \vec{x} = \vec{b}$$

rhs (usually external excitation)

unknown (physics we want)

how your system responds

(EM, fluids, etc + boundary conditions)

• Examples

$$\nabla^2 \phi = -f$$

Poisson eq.

$$\square \psi = f$$

Wave eq. (w/ source)

$$\left(m \frac{d^2}{dt^2} + k\right) x = F(t)$$

Forced HO

In all these cases our job is to somehow put the diff. op. on the other side of the eq. to find the unknown. That amounts to finding the inverse.

